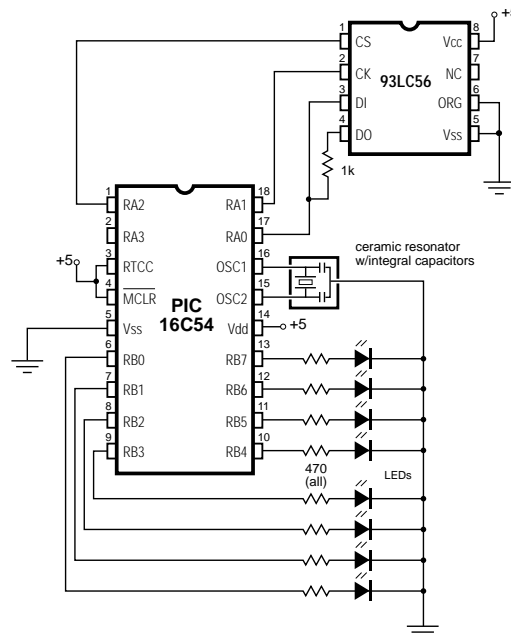


Using Serial EEPROMs

Introduction. This application note shows how to use the Microchip 93LC56 EEPROM to provide 256 bytes of nonvolatile storage. It provides a tool kit of subroutines for reading, writing, and erasing the EEPROM. (Note that EEPROMs made by other manufacturers will not work with the PIC16Cxx.)

Background. Many designs take advantage of the PIC's ability to store tables of data in its EPROM program memory. The trouble is that the larger the tables are, the smaller the space left for code. And many applications could benefit from the ability to occasionally update data tables for calibration or other purposes. What the PIC needs is the equivalent of a tiny disk drive.



The Microchip 93C56 and 93LC56 electrically erasable PROMs (EEPROMs) are perfect for these applications. They communicate serially via a three- or four-wire bus using a simple synchronous (clocked) communication protocol at rates of up to 2 million bits per

second (Mbps). It's possible to read a byte in as little as 10 microseconds (including the time required to send the instruction opcode and address). Once a program has begun reading data from the EEPROM, it can continue reading subsequent bytes without stopping. These are clocked in at the full 2 Mbps rate; 1 byte every 4 microseconds.

Erasing and writing these serial EEPROMs happens at a more leisurely pace. While the opcode, address, and data can be clocked into the chip at high speed, the EEPROM requires about 2 milliseconds to erase or write a byte. During this time, the chip cannot process additional instructions. The PIC can poll a flag to determine when the automatic erase/write programming cycle is over. As soon as this flag goes high, the EEPROM is ready for more instructions.

Data stored in the EEPROM will be retained for 10 years or more, according to the manufacturer. The factor that determines the EEPROM's longevity in a particular application is the number of erase/write cycles. Depending on factors such as temperature and supply voltage, the EEPROM is good for 10,000 to 1 million erase/write cycles. This rules out its use as a substitute for ordinary RAM, since many PIC applications write to RAM thousands of times a second. At that rate, the EEPROM could be unusable in as little as 20 seconds! For a thorough discussion of EEPROM endurance, see the Microchip Embedded Control Handbook, publication number DS00092A, October 1992.

How it works. The circuit in the figure specifies a 93LC56 EEPROM, but a 93C56 will work as well. The difference is that the LC device has a wider Vcc range (2.5–5.5 V, versus 4–5.5 V), lower current consumption (3 mA versus 4 mA), and can be somewhat slower in completing internal erase/write operations, presumably at lower supply voltages. In general, the LC type is less expensive, and a better match for the operating characteristics of the PIC.

The schematic shows the data in and data out (DI, DO) lines of the EEPROM connected together to a single PIC I/O pin. The 1k resistor prevents the PIC and DO from fighting over the bus during a read operation. During a read, the PIC sends an opcode and an address to the EEPROM. As soon as it has received the address, the EEPROM activates DO and puts a 0 on it. If the last bit of the address is a 1, the PIC

could end up sourcing current to ground through the EEPROM. The resistor limits the current to a reasonable level.

The program listing is a collection of subroutines for reading, writing, and erasing the EEPROM. All of these rely on *Shout*, a routine that shifts bits out to the EEPROM. To perform an EEPROM operation, the software loads the number of clock cycles into *clocks* and the data to be output into *temp*. It then calls *Shout*, which does the rest.

If you don't have the EEPROM data handy (Microchip Data Book, DS00018D, 1991), you should know about a couple of subtleties. First, when the EEPROM powers up, it is write protected. You must call *EEnable* before trying to write or erase it. It's a good idea to call *EEdisbl* (disable writes) as soon as possible after you're done. Otherwise, a power glitch could alter the contents of your EEPROM. Also, you cannot write all locations (*EEWral*) without first erasing all locations (*EEwipe*).

Modifications. The table of constants at the beginning of the listing specifies the opcodes for each of the EEPROM operations. Although the opcodes are only three bits long, they are combined with a trailing don't-care bit. This bit is required for compatibility with the 512-byte 93LC66. With the '66, this would be address bit A8. If you want to modify this code for the '66, add a line to the read, write, and byte erase routines to copy A8 into bit 4 of *temp* just before calling *Shout*. If you want to increase capacity by adding more EEPROMs, you can bus the data and clock lines together and provide separate chip selects to each device.

If you plan to run your PIC faster than 8 MHz, add one or two *nops* where marked in the listing. The clock must be high for at least 500 nanoseconds. The low time must also be greater than 500 ns, but the move-data, rotate, and looping instructions provide enough delay.

Program listing. This program may be downloaded from our Internet ftp site at <ftp.tech-tools.com>. The ftp site may be accessed directly or through our web site at <http://www.tech-tools.com>.

; PROGRAM: EEPROM.SRC

; This program is a collection of subroutines for reading, writing, and erasing the
 ; 93LC56 (or 'C56) serial EEPROM. As a demonstration, it writes a scanning pattern
 ; to the 256 bytes of the EEPROM, and then reads it back to eight LEDs connected
 ; to port rb.

; Remember to change device info when programming part

	device	pic16c54,xt_osc,wdt_off,protect_off	
	reset	start	
D	=	ra.0	; Pins DI and DO of the EEPROM
CLK	=	ra.1	; Clock pin--data valid on rising ; edge
CS	=	ra.2	; Chip select--high = active
ROP	=	192	; Opcode for read
WROP	=	160	; Opcode for write
EWEN	=	152	; Opcode to enable erase and ; write
EWDS	=	128	; Opcode to disable erase and ; write
ERAS	=	224	; Opcode to erase a byte
ERAL	=	144	; Opcode to erase all bytes
WRAL	=	136	; Opcode to write all bytes with ; specified data
	org	8	
temp	ds	1	; Temporary variable for EE ; routines
EEdata	ds	1	; Passes data to EEwrite/wrall, ; from EEread
EEaddr	ds	1	; Passes address to EEerase, ; EEwrite, EEread
clocks	ds	1	; Number of clock cycles for ; ShiftOUT
tick1	ds	1	; Timer for Delay--not required for ; EE routines
tick2	ds	1	; Timer for Delay--not required for ; EE routines
	org	0	
start	mov	ra,#0	; Clear ports
	mov	rb,#0	
	mov	!ra,#0	; Make all ra pins outputs initially
	mov	!rb,#0	
	call	EEnable	; Turn off write/erase protection
	mov	EEdata,#1	
	mov	EEaddr,#0	
:loop	call	EEwrite	; Write scanning pattern to ; EEPROM

```

                                call    Busy
                                rr      EEdata
                                ijnz    EEaddr, :loop
                                call    EEdisbl          ; Turn write/erase protection back
                                                         ; on
:loop2      mov     EEaddr, #0
            call    EEread
            mov     rb, EEdata
            inc     EEaddr
            call    delay
            goto    :loop2

; Shift out the bits of temp to the EEPROM data line.
Shout      rl      temp          ; Rotate bit7 of temp into carry
            movb    D, c          ; Move carry bit to input of
                                     ; EEPROM
            setb    CLK          ; Clock the bit into EEPROM
            nop     ; Clock must be high > 500 ns
            clrb    CLK
            djnz    clocks, Shout
            ret

; Read the byte in EEaddr into EEdata.
EEread     mov     temp, #ROP      ; Move the read opcode into temp

            mov     clocks, #4      ; Number of bits to shift out (op+1)
            setb    CS
            call    Shout
            mov     clocks, #8
            mov     temp, EEaddr
            call    Shout
            mov     !ra, #1
            mov     clocks, #8
:read      setb    CLK
            movb    c, D
            rl      temp
            clrb    CLK
            djnz    clocks, :read
            mov     EEdata, temp
            mov     !ra, #0
            clrb    CS
            ret

; Call to unprotect after EEdisbl or power up.
EEnable    setb    CS
            mov     clocks, #12
            mov     temp, #EWEN
            call    Shout
            clrb    CS

```

ret

; Call to protect against accidental write/erasure.

```
EEdisbl    setb    CS
           mov     clocks,#12
           mov     temp,#EWDS
           call    Shout
           clrb    CS
           ret
```

; Write the byte in EEdata to EEaddr.

```
EEwrite mov  temp,#WROP
           mov     clocks,#4
           setb    CS
           call    Shout
           mov     clocks,#8
           mov     temp,EEaddr
           call    Shout
           mov     clocks,#8
           mov     temp,EEdata
           call    Shout
           clrb    CS
           ret
```

; Erase the byte in EEaddr. Erasure leaves FFh (all 1s) in the byte.

```
EEerase    mov     temp,#ERAS
           mov     clocks,#4
           setb    CS
           call    Shout
           mov     clocks,#8
           mov     temp,EEaddr
           call    Shout
           ret
```

; Erase the entire EEPROM--all 256 bytes. Call before using EEwrrall below.

```
EEwipe     setb    CS
           mov     temp,#ERAL
           mov     clocks,#12
           call    Shout
           clrb    CS
           ret
```

; Write the byte in EEdata to every address. Call EEwipe first.

```
EEwrrall   setb    CS
           mov     temp,#WRAL
           mov     clocks,#12
           call    Shout
           mov     clocks,#8
           mov     temp,EEdata
```

```

                                call    Shout
                                clrb    CS
                                ret

; Check flag to determine whether the EEPROM has finished its self-timed erase/
; write. Caution: This will lock up your program until D goes high.
Busy    nop
        mov    !ra,#1
        setb   CS
:wait    jnb    D,:wait
        clrb   CS
        mov    !ra,#0
        ret

Delay    djnz   tick1,Delay    ; Delay routine for demo.
        djnz   tick2,Delay
        ret
```